

# ASHISH RAO MANGALORE

🌐 <https://ashishrao7.github.io/ashish-rao/>

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EDUCATION	<b>Master of Science in Neuroengineering (MSNE),</b> <i>Technische Universität München, München, Germany</i>	<b>Oct 2019- Present</b>
	<b>Bachelor of Engineering in Electrical and Electronics</b> <i>R.V College of Engineering, Bengaluru, KA, India</i>	<b>Aug 2012- May 2016</b>
INTERESTS	Brain Computer Interfaces, Prosthetics, Event Based Cameras, Signal Processing, Computational Neuroscience, Neural Engineering, Machine Learning, Robotics	
PROJECT CONTRIBUTIONS	<b>Implementation of Proximity Operators and ISTA in ELSA</b> <ul style="list-style-type: none"><li>Contributed to ELSA, a tomographic Reconstruction software developed at the <a href="https://gitlab.lrz.de/IP/elsa">Department of Informatics, TUM (https://gitlab.lrz.de/IP/elsa)</a></li><li>Designed, Implemented and tested Proximity Operators (Soft-Thresholding), LASSO problem and the ISTA Solver in C++</li></ul> <b>Maintainer of TUMBrain</b> <ul style="list-style-type: none"><li>Maintaining and Architecting a software repository developed at ICS, TUM for EEG signal classification to control game avatars</li></ul>	
PROFESSIONAL EXPERIENCE	<b>Visiting Researcher</b> <i>Max Planck Institute for Brain and Research, Frankfurt Am Main</i>	<b>Oct 2020- Dec 2020</b>
	<ul style="list-style-type: none"><li>Working on plasticity in Inhibition Stabilized recurrent networks with noisy inputs in Prof. Dr. Julijana Gjorgjieva's group.</li></ul>	
	<b>Teaching Assistant for Neurorehabilitation</b> <i>Institute of Cognitive Systems, Technische Universität München</i>	<b>Jul 2020- Dec 2020</b>
	<ul style="list-style-type: none"><li>Design Tutorials for the neurorehabilitation course</li><li>Sourcing of materials for building a robotic exoskeleton for rehabilitation</li><li>Designing experiments with hardware and software for the exoskeleton</li></ul>	
	<b>Research Assistant</b> <i>Indian Institute of Science, Bengaluru</i>	<b>Sept 2018- Oct 2019</b>
	<ul style="list-style-type: none"><li>Research on 3-D Object Reconstruction Methods with Neuromorphic Cameras with Prof. Chandrasekhar Seelamantula and Prof. Chetan Singh Thakur. Developed a new method using structured light which was faster than the SOTA by a factor of n. (<a href="https://github.com/ashishrao7/NFPP">https://github.com/ashishrao7/NFPP</a>)</li><li>Contributed to preliminary experiments on a Sampling theory for Neuromorphic Sensors</li></ul>	
	<b>Associate Software Engineer</b> <i>Robert Bosch Engineering and Business Services, Bengaluru</i>	<b>Sep 2016- May 2018</b>

	<ul style="list-style-type: none"> <li>• Carried out energy analytics for industrial plants.</li> <li>• Planned and ran analyses for optimizing the energy consumption of plants</li> <li>• Worked on demand forecasting using LSTMs to help stakeholders estimate energy to be purchased for the next day.</li> <li>• Automated processes to generate and keep track of part numbers for the machine building team.</li> </ul>	
	<b>Intern</b> <i>Robert Bosch Engineering and Business Services, Bengaluru</i>	<b>Jan 2016- Apr 2016</b>
	<ul style="list-style-type: none"> <li>• Worked on reducing error in solar panel temperature predictions. Developed models using regression and ANNs.</li> <li>• Developed a workflow to visualize the trend of the collected data points available at each second throughout the day using MATLAB and Simulink.</li> </ul>	
<b>PUBLICATIONS</b>	<b>A. Rao Mangalore</b> , C.S. Seelamantula, and C.S. Thakur, "Neuromorphic Fringe Projection Profilometry", Signal Processing Letters, September, 2020	
	A. B. Harish, G. M. Deepak, <b>A. Rao Mangalore</b> , and C.S. Seelamantula, "Depth Estimation using the Riesz Transform", To be submitted to IEEE Transactions on Computational Imaging	
	R. Vijaykumar, R. Rudramoorthy, and <b>A. Rao Mangalore</b> , (2017). Prediction of solar PV panel temperature using mathematical models and artificial neural networks. Journal of Computational and Theoretical Nanoscience 14, 4986–4997.	
<b>HONORS &amp; AWARDS</b>	<b>Deutschland Stipendium, TU München</b> <span style="float: right;"><b>2020</b></span> Merit based Scholarship for talented and high-achieving students at public and state recognised universities in Germany <span style="float: right;"><b>-2021</b></span>	
	<b>Invited Speaker SPCOM 2020 - International Conference on Signal Processing and Communications</b> Talk titled "Object Scanning and the Dynamic Vision Sensor"	<b>Jul 2020</b>
	<b>1st IEEE Brain BR41N.IO Prize at BR41N.IO Brain-Computer Interface Designers' Hackthon 2020</b> Awarded 1st Place in the Programming Projects category of the hackathon for our solution VibeLight.	<b>Jun 2020</b>
	<b>3rd in the Graduating Batch of EEE, RVCE</b> Placed 3rd on the basis of 4 year CGPA at the end of the undergraduate course among the graduating batch of 63 students	<b>2016</b>
	<b>4th in Sparkfun Autonomous Vehicle Challenge</b> Placed 4th in the autonomous vehicle challenge organized by spark fun electronics at Denver, Colorado	<b>Jul 2015</b>
	<b>40th at DBF 2015, AIAA</b> Represented the College Aerodesign team at the Prestigious Design/Build/Fly 2015 contest organized by AIAA in Tucson, Arizona. Finished 40th out of 100 teams	<b>Apr 2015</b>
<b>TECHNICAL</b>	<b>Programming Languages</b>	<i>Python, C++17, C, Matlab</i>
	<b>Frameworks</b>	<i>Pandas, Keras, Pytorch, ROS</i>

<b>SKILLS</b>	<b>Computer Aided Design</b>	<i>Autodesk Fusion 360, EagleCAD</i>
	<b>Other</b>	<i>ArduPilot, Arduino, Raspberry Pi Git, LaTeX</i>
<b>EXTRA-CURRICULAR ACTIVITIES</b>	<b>Avionics Engineer</b> <i>Project Vyoma, Aerodesign Team, RVCE</i>	<b>Apr 2013-May 2016</b>
	<ul style="list-style-type: none"> <li>• Made unmanned arial vehicles (fixed-wing and rotory) flight ready.</li> <li>• Deployed autonomous UAVs (fixed-wing and rotory) using the Ardupilot/Pixhawk platform.</li> <li>• Carried out conceptual design of a solar powered fixed wing UAV which was later fabricated in the workshop and tested.</li> <li>• Built and deployed arial photography ready drones to be be used for filming RVCE's college fest.</li> <li>• Built a thrust rig to test thrust generated by different motor-propellor combinations</li> <li>• Participated in international competitions representing the college.</li> </ul>	
<b>COLLEGE SERVICE</b>	<b>Mentor and Avionics Team Lead</b> <i>Project Vyoma, Aerodesign Team, RVCE</i>	<b>Aug 2014-May 2016</b>
	<ul style="list-style-type: none"> <li>• Oversaw day to day activities of the electronics subsection of the team</li> <li>• Mentored new recruits to the team and oversaw their development</li> <li>• Interacted with sponsors to raise funding for the operation of the team</li> </ul>	
<b>COLLEGE SERVICE</b>	<b>Buddy Program Co-ordinator</b> <i>Institute of Cognitive Systems, TUM</i>	<b>Aug 2020-Nov 2020</b>
	<ul style="list-style-type: none"> <li>• Facilitating integration of freshmen joining the Master of Science in Neuroengineering at TUM in the winter of 2020</li> </ul>	
<b>COLLEGE SERVICE</b>	<b>Student Placement Co-ordinator</b> <i>Dept of Electrical and Electronics Engineering, RVCE</i>	<b>Aug 2015-Jun 2016</b>
	<ul style="list-style-type: none"> <li>• Co-ordinated between students of Electrical &amp; Electronics Engineering and the Placement Dept of RVCE for the smooth functioning of the placement process.</li> <li>• Managed hosting of visiting employers, scheduling of events and addressed concerns and grievances of all parties involved in the placement process.</li> </ul>	
<b>CERTIFICATIONS</b>	<b>Reinforcement Learning</b> (Center for Continuing Education, IISc)	<b>Aug 2018-Dec 2018</b>
	<b>Deep Learning Specialisation</b> <i>Coursera</i>	<b>2018</b>
	<b>Machine Learning Engineer Nanodegree</b> <i>Udacity</i>	<b>2017</b>
	<b>Build a Modern Computer from First Principles: From Nand to Tetris</b> <i>Hebrew University of Jerusalem, Coursera</i>	<b>2017</b>
	<b>edX Honor Code Certificate for Circuits and Electronics</b> <i>edx:MITx</i>	<b>2013</b>
	<b>edX Honor Code Certificate for Electricity and Magnetism</b> <i>edx:MITx</i>	<b>2013</b>

<b>LANGUAGES KNOWN</b>	<b>English</b>	<i>Native or bilingual proficiency</i>
	<b>German</b>	<i>A2 Level Proficiency, Certified by Göethe Institut</i>
	<b>Kannada</b>	<i>Native or bilingual proficiency</i>
	<b>Hindi</b>	<i>Professional working Proficiency</i>